

# HT12A/HT12E 2<sup>12</sup> Series of Encoders

#### **Features**

- · Operating voltage
  - 2.4V~5V for the HT12A
  - 2.4V~12V for the HT12E
- Low power and high noise immunity CMOS technology
- Low standby current: 0.1μA (typ.) at V<sub>DD</sub>=5V
- HT12A with a 38kHz carrier for infrared transmission medium.
- · Minimum transmission word
  - Four words for the HT12E
  - One word for the HT12A
- · Built-in oscillator needs only 5% resistor
- · Data code has positive polarity
- Minimal external components
- Pair with Holtek's 2<sup>12</sup> series of decoders
- 18-pin DIP, 20-pin SOP package

#### **Applications**

- · Burglar alarm system
- · Smoke and fire alarm system
- · Garage door controllers
- · Car door controllers

- Car alarm system
- · Security system
- · Cordless telephones
- · Other remote control systems

#### **General Description**

The 2<sup>12</sup> encoders are a series of CMOS LSIs for remote control system applications. They are capable of encoding information which consists of N address bits and 12–N data bits. Each address/data input can be set to one of the two logic states. The programmed addresses/data are transmitted together with the header

bits via an RF or an infrared transmission medium upon receipt of a trigger signal. The capability to select a  $\overline{\text{TE}}$  trigger on the HT12E or a DATA trigger on the HT12A further enhances the application flexibility of the  $2^{12}$  series of encoders. The HT12A additionally provides a 38kHz carrier for infrared systems.

#### **Selection Table**

Function Part No.	Address No.	Address/ Data No.	Data No.	Oscillator	Trigger	Carrier Output	Negative Polarity	Package
HT12A	8	0	4	455kHz resonator	D8~D11	38kHz	No	18DIP, 20SOP
HT12E	8	4	0	RC oscillator	TE	No	No	18DIP, 20SOP

Note: Address/Data represents pins that can be either address or data according to the application requirement.

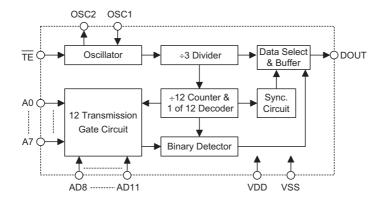
Rev. 1.20 1 February 20, 2009



#### **Block Diagram**

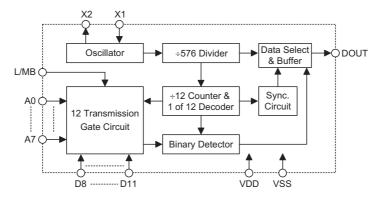
#### **TE** Trigger

HT12E



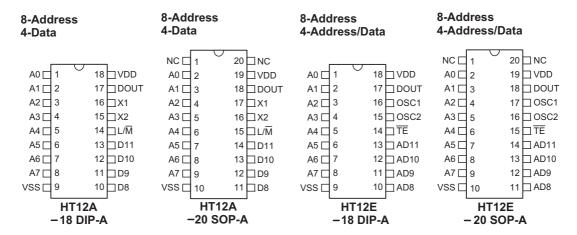
#### **DATA Trigger**

HT12A



Note: The address data pins are available in various combinations (refer to the address/data table).

#### **Pin Assignment**





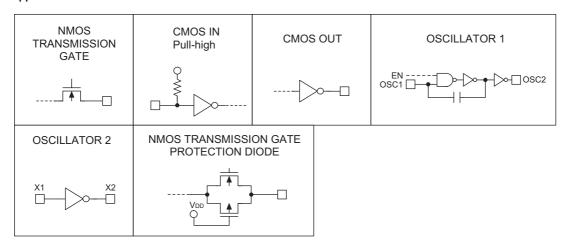
#### **Pin Description**

Pin Name	I/O	Internal Connection	Description
A0~A7	I	CMOS IN Pull-high (HT12A)	Input pins for address A0~A7 setting These pins can be externally set to VSS or left open
		NMOS TRANSMISSION GATE PROTECTION DIODE (HT12E)	
AD8~AD11	I	NMOS TRANSMISSION GATE PROTECTION DIODE (HT12E)	Input pins for address/data AD8~AD11 setting These pins can be externally set to VSS or left open
D8~D11	I	CMOS IN Pull-high	Input pins for data D8~D11 setting and transmission enable, active low These pins should be externally set to VSS or left open (see Note)
DOUT	0	CMOS OUT	Encoder data serial transmission output
L/M	I	CMOS IN Pull-high	Latch/Momentary transmission format selection pin: Latch: Floating or VDD Momentary: VSS
TE	ı	CMOS IN Pull-high	Transmission enable, active low (see Note)
OSC1	I	OSCILLATOR 1	Oscillator input pin
OSC2	0	OSCILLATOR 1	Oscillator output pin
X1	1	OSCILLATOR 2	455kHz resonator oscillator input
X2	0	OSCILLATOR 2	455kHz resonator oscillator output
VSS	ı	_	Negative power supply, ground
VDD	ı	_	Positive power supply

Note: D8~D11 are all data input and transmission enable pins of the HT12A.

TE is a transmission enable pin of the HT12E.

#### **Approximate Internal Connections**





#### **Absolute Maximum Ratings**

Supply Voltage (HT12A) $V_{SS}$ -0.3V to $V_{SS}$ +5.5V	Supply Voltage (HT12E)0.3V to 13V
Input VoltageV <sub>SS</sub> -0.3 to V <sub>DD</sub> +0.3V	Storage Temperature50°C to 125°C
Operating Temperature–20°C to 75°C	

Note: These are stress ratings only. Stresses exceeding the range specified under "Absolute Maximum Ratings" may cause substantial damage to the device. Functional operation of this device at other conditions beyond those listed in the specification is not implied and prolonged exposure to extreme conditions may affect device reliability.

#### **Electrical Characteristics**

**HT12A** Ta=25°C

Cumbal	Parameter	Test Cor		Min.	Turn	Max.	Unit
Symbol	Parameter	$V_{DD}$	Conditions	IVIIII.	Тур.	wax.	Unit
$V_{DD}$	Operating Voltage	_	_	2.4	3	5	V
	Charadha Camarah	3V	Os sillatar atara	_	0.1	1	μΑ
I <sub>STB</sub>	Standby Current	5V	Oscillator stops	_	0.1	1	μΑ
	0	3V	3V No load -	_	200	400	μΑ
I <sub>DD</sub>	Operating Current	5V	5V f <sub>OSC</sub> =455kHz		400	800	μА
	0.1.15: 0.1	<b>5</b> , ,	V <sub>OH</sub> =0.9V <sub>DD</sub> (Source)	-1	-1.6	_	mA
I <sub>DOUT</sub>	Output Drive Current	5V	V <sub>OL</sub> =0.1V <sub>DD</sub> (Sink)	2	3.2	_	mA
V <sub>IH</sub>	"H" Input Voltage	_	_	0.8V <sub>DD</sub>	_	$V_{DD}$	V
V <sub>IL</sub>	"L" Input Voltage	_	_	0	_	0.2V <sub>DD</sub>	V
R <sub>DATA</sub>	D8~D11 Pull-high Resistance	5V	V <sub>DATA</sub> =0V	_	150	300	kΩ

**HT12E** Ta=25°C

Cumbal	Parameter		Test Conditions	Min	Tres	Max	Unit	
Symbol	Parameter	V <sub>DD</sub>	Conditions	Min.	Тур.	Max.	Onit	
$V_{DD}$	Operating Voltage	_	_	2.4	5	12	V	
	011	3V	O a a Warten and a mark	_	0.1	1	μΑ	
I <sub>STB</sub>	Standby Current	12V	Oscillator stops	_	2	4	μА	
	0 " 0 '	3V	National 6 - Old In	_	40	80	μΑ	
I <sub>DD</sub>	Operating Current		No load, f <sub>OSC</sub> =3kHz	_	150	300	μΑ	
	0.110:01	5) (	V <sub>OH</sub> =0.9V <sub>DD</sub> (Source)	-1	-1.6	_	mA	
I <sub>DOUT</sub>	Output Drive Current	5V	V <sub>OL</sub> =0.1V <sub>DD</sub> (Sink)	1	1.6	_	mA	
V <sub>IH</sub>	"H" Input Voltage	_	_	0.8V <sub>DD</sub>	_	$V_{DD}$	V	
V <sub>IL</sub>	"L" Input Voltage	_	_	0	_	0.2V <sub>DD</sub>	V	
f <sub>OSC</sub>	Oscillator Frequency	5V	$R_{OSC}$ =1.1 $M\Omega$	_	3	_	kHz	
R <sub>TE</sub>	TE Pull-high Resistance	5V	V <sub>TE</sub> =0V	_	1.5	3	ΜΩ	

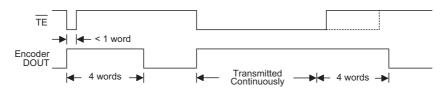
Rev. 1.20 4 February 20, 2009



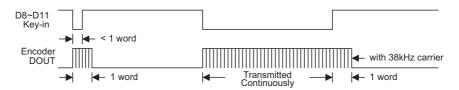
#### **Functional Description**

#### Operation

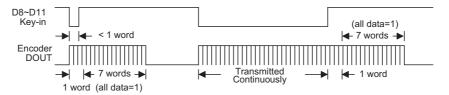
The  $2^{12}$  series of encoders begin a 4-word transmission cycle upon receipt of a transmission enable ( $\overline{\text{TE}}$  for the HT12E or D8~D11 for the HT12A, active low). This cycle will repeat itself as long as the transmission enable ( $\overline{\text{TE}}$  or D8~D11) is held low. Once the transmission enable returns high the encoder output completes its final cycle and then stops as shown below.



Transmission timing for the HT12E



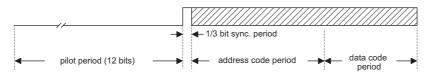
Transmission timing for the HT12A (L/M=Floating or VDD)



Transmission timing for the HT12A (L/M=VSS)

#### **Information Word**

If  $L/\overline{M}=1$  the device is in the latch mode (for use with the latch type of data decoders). When the transmission enable is removed during a transmission, the DOUT pin outputs a complete word and then stops. On the other hand, if  $L/\overline{M}=0$  the device is in the momentary mode (for use with the momentary type of data decoders). When the transmission enable is removed during a transmission, the DOUT outputs a complete word and then adds 7 words all with the "1" data code. An information word consists of 4 periods as illustrated below.



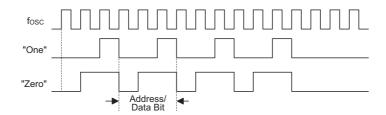
Composition of information

Rev. 1.20 5 February 20, 2009

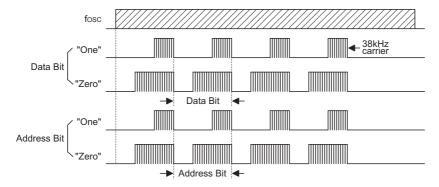


#### Address/Data Waveform

Each programmable address/data pin can be externally set to one of the following two logic states as shown below.



Address/Data bit waveform for the HT12E



Address/Data bit waveform for the HT12A

The address/data bits of the HT12A are transmitted with a 38kHz carrier for infrared remote controller flexibility.

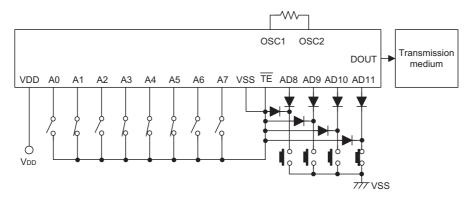
#### Address/Data Programming (Preset)

The status of each address/data pin can be individually pre-set to logic "high" or "low". If a transmission-enable signal is applied, the encoder scans and transmits the status of the 12 bits of address/data serially in the order A0 to AD11 for the HT12E encoder and A0 to D11 for the HT12A encoder.

During information transmission these bits are transmitted with a preceding synchronization bit. If the trigger signal is not applied, the chip enters the standby mode and consumes a reduced current of less than  $1\mu A$  for a supply voltage of 5V.

Usual applications preset the address pins with individual security codes using DIP switches or PCB wiring, while the data is selected by push buttons or electronic switches.

The following figure shows an application using the HT12E:



Rev. 1.20 6 February 20, 2009



The transmitted information is as shown:

Pilot	A0	A1	A2	A3	A4	A5	A6	A7	AD8	AD9	AD10	AD11
& Sync.	1	0	1	0	0	0	1	1	1	1	1	0

#### Address/Data Sequence

The following provides the address/data sequence table for various models of the 2<sup>12</sup> series of encoders.

Part No.					Δ	\ddress/	Data Bit	s				
Part No.	0	1	2	3	4	5	6	7	8	9	10	11
HT12A	A0	A1	A2	А3	A4	A5	A6	A7	D8	D9	D10	D11
HT12E	A0	A1	A2	A3	A4	A5	A6	A7	AD8	AD9	AD10	AD11

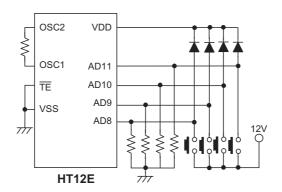
#### **Transmission Enable**

For the HT12E encoders, transmission is enabled by applying a low signal to the  $\overline{\text{TE}}$  pin. For the HT12A encoders, transmission is enabled by applying a low signal to one of the data pins D8~D11.

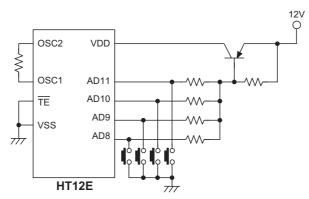
#### **Two Erroneous HT12E Application Circuits**

The HT12E must follow closely the application circuits provided by Holtek (see the "Application circuits").

• Error: AD8~AD11 pins input voltage > V<sub>DD</sub>+0.3V



• Error: The IC's power source is activated by pins AD8~AD11

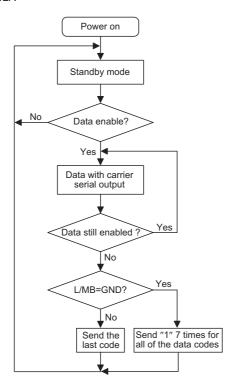


Rev. 1.20 7 February 20, 2009

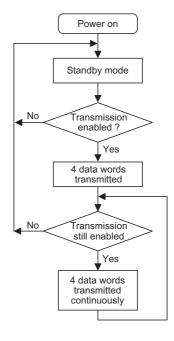


#### Flowchart

• HT12A



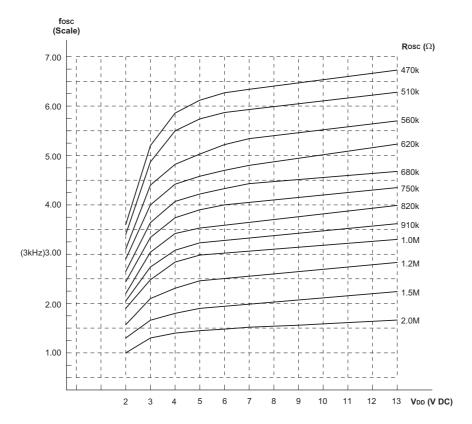
• HT12E



Note: D8~D11 are transmission enables of the HT12A.  $\overline{\text{TE}}$  is the transmission enable of the HT12E.

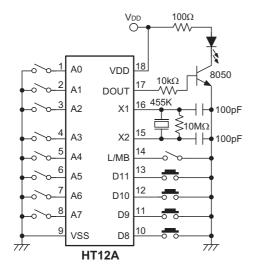


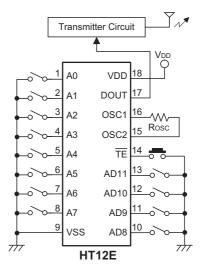
#### Oscillator Frequency vs. Supply Voltage



The recommended oscillator frequency is  $f_{OSCD}$  (decoder)  $\cong 50 \; f_{OSCE}$  (HT12E encoder)  $\cong \frac{1}{3} \; f_{OSCE}$  (HT12A encoder)

#### **Application Circuits**

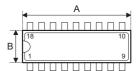


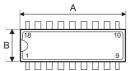


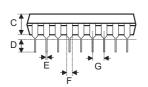


#### **Package Information**

#### 18-pin DIP (300mil) Outline Dimensions









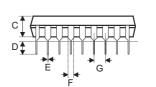




Fig1. Full Lead Packages

Fig2. 1/2 Lead Packages

#### • MS-001d (see fig1)

Sumbal		Dimensions in mil	
Symbol	Min.	Nom.	Max.
A	880	_	920
В	240	_	280
С	115	_	195
D	115	_	150
E	14	_	22
F	45	_	70
G	_	100	_
Н	300	_	325
I	_	_	430

#### • MS-001d (see fig2)

Complete		Dimensions in mil						
Symbol	Min.	Nom.	Max.					
А	845	_	880					
В	240	_	280					
С	115	_	195					
D	115	_	150					
E	14	_	22					
F	45	_	70					
G	_	100	_					
Н	300	_	325					
I	_	_	430					

Rev. 1.20 10 February 20, 2009



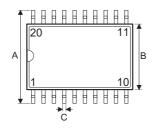
#### • MO-095a (see fig2)

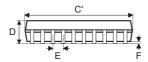
Symbol		Dimensions in mil	
Symbol	Min.	Nom.	Max.
Α	845	_	885
В	275	_	295
С	120	_	150
D	110	_	150
E	14	_	22
F	45	_	60
G	_	100	_
Н	300	_	325
I	_	_	430

Rev. 1.20 11 February 20, 2009



#### 20-pin SOP (300mil) Outline Dimensions







#### • MS-013

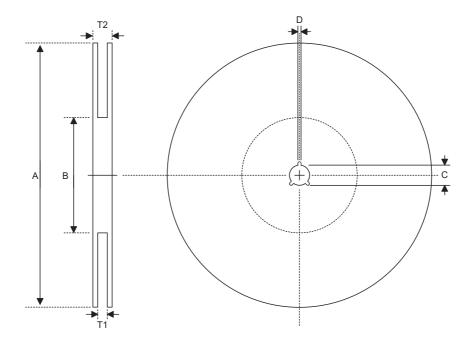
Symbol		Dimensions in mil	
Symbol	Min.	Nom.	Max.
Α	393	_	419
В	256	_	300
С	12	_	20
C'	496	_	512
D	_	_	104
E	_	50	_
F	4	_	12
G	16	_	50
Н	8	_	13
α	0°	_	8°

Rev. 1.20 12 February 20, 2009



### **Product Tape and Reel Specifications**

#### **Reel Dimensions**



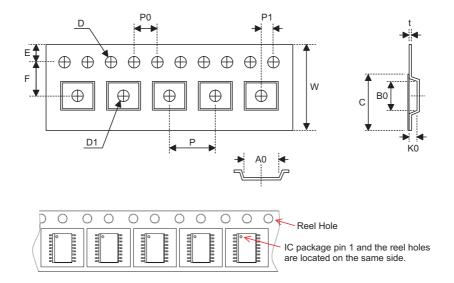
#### SOP 20W

Symbol	Description	Dimensions in mm	
Α	Reel Outer Diameter	330.0±1.0	
В	Reel Inner Diameter	100.0±1.5	
С	Spindle Hole Diameter	13.0 <sup>+0.5/-0.2</sup>	
D	Key Slit Width	2.0±0.5	
T1	Space Between Flange	24.8 <sup>+0.3/-0.2</sup>	
T2	Reel Thickness	30.2±0.2	

Rev. 1.20 13 February 20, 2009



#### **Carrier Tape Dimensions**



#### SOP 20W

Symbol	Description	Dimensions in mm
W	Carrier Tape Width	24.0 <sup>+0.3/-0.1</sup>
Р	Cavity Pitch	12.0±0.1
E	Perforation Position	1.75±0.10
F	Cavity to Perforation (Width Direction)	11.5±0.1
D	Perforation Diameter	1.5 <sup>+0.1/-0.0</sup>
D1	Cavity Hole Diameter	1.50 <sup>+0.25/-0.00</sup>
P0	Perforation Pitch	4.0±0.1
P1	Cavity to Perforation (Length Direction)	2.0±0.1
A0	Cavity Length	10.8±0.1
В0	Cavity Width	13.3±0.1
K0	Cavity Depth	3.2±0.1
t	Carrier Tape Thickness	0.30±0.05
С	Cover Tape Width	21.3±0.1

Rev. 1.20 14 February 20, 2009



Copyright © 2009 by HOLTEK SEMICONDUCTOR INC.

The information appearing in this Data Sheet is believed to be accurate at the time of publication. However, Holtek assumes no responsibility arising from the use of the specifications described. The applications mentioned herein are used solely for the purpose of illustration and Holtek makes no warranty or representation that such applications will be suitable without further modification, nor recommends the use of its products for application that may present a risk to human life due to malfunction or otherwise. Holtek's products are not authorized for use as critical components in life support devices or systems. Holtek reserves the right to alter its products without prior notification. For the most up-to-date information, please visit our web site at http://www.holtek.com.tw.

Rev. 1.20 15 February 20, 2009

# HandsOn Technology

http://www.handsontec.com

creativity for tomorrow's better living...

## www.handsontec.com

# Welcome to Handsontec Store



LCD+Keyboard Shield



10-Segments LED Bar Display



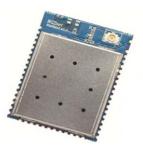
**Ethernet Module** 



Arduino Uno



MicroSD Breakout Board



WiFi Module



20x4 LCD Display Module



Stepper Motor Driver



**PWM Motor Speed Controller** 



Breakout Board & Modules



**Integrated Circuits** 



**Discrete Parts** 



**Assembled Kits** 



**Connectors**